

SCT-1SX Series

Firmware version 01.21.01

Fieldbus Protocol



© Rice Lake Weighing Systems. All rights reserved.

Rice Lake Weighing Systems® is a registered trademark of
Rice Lake Weighing Systems.

All other brand or product names within this publication are trademarks or
registered trademarks of their respective companies.

All information contained within this publication is, to the best of our knowledge, complete and accurate at the
time of publication. Rice Lake Weighing Systems reserves the right to make changes to the technology, features,
specifications and design of the equipment without notice.

The most current version of this publication, software, firmware and all other product
updates can be found on our website:

www.ricelake.com

| | |
|---|----------|
| Connection | 4 |
| Fieldbus and Data Format Configuration | 5 |
| Data Reading (Input Area) | 7 |
| Alibi Memory "Page 1000" (0x03E8) | 9 |
| ADC Value "Page 3000" (0x0BB8) | 10 |
| µV Value "Page 3001" (0x0BB9) | 11 |
| Calibration 0 - Scale Parameters "Page 5000" (0x1388) | 12 |
| Calibration 1 - Calibration Points Weights "Page 5001" (0x1389) | 13 |
| Calibration 2 - Calibration Points ADC "Page 5002" (0x138A) | 14 |
| Calibration 3 - Legal State "Page 5003" (0x138B) | 15 |
| Calibration 4 - Filter and Metrical Parameters (1/2) "Page 5004" (0x138C) | 16 |
| Calibration 5 - Metrical Parameters (2/2) "Page 5005" (0x138D) | 17 |
| Calibration 6 - Condensed Calibration "Page 5006" (0x138E) | 18 |
| Advanced Filters "Page 5007" (0x138F) | 19 |
| Anti-Peak Filter "Page 5008" (0x139A) | 20 |
| Tare Type "Page 5010" (0x1392) | 21 |
| Transmitter SN and Firmware "Page 5011" (0x1393) | 22 |
| Unit of Measure 2 ("ConUEr" mode) "Page 5015" (0x1397) | 23 |
| Fieldbus Configuration "Page 5030" (0x13A6) | 24 |
| Profinet Name (only for SCT-1SX-PRONET) "Page 5031" (0x13A7) | 25 |
| Inputs Configuration "Page 5100" (0x13EC) | 26 |
| Outputs Configuration "Pages 5101 - 5104" (0x13ED - 13F0) | 27 |
| Analogue Output Configuration (1/3) "Page 5101" (0x13F6) | 28 |
| Analogue Output Configuration (2/3) "Page 5102" (0x13F7) | 29 |
| Analogue Output Configuration (3/3) "Page 5102" (0x13F8) | 30 |
| Setpoint Values (1/2) "Page 6100" (0x17D4) | 31 |

| | |
|---|-----------|
| Setpoint Values (2/2) "Page 6101" (0x17D5) | 32 |
| <i>Table 1 - Input Status Register</i> | 33 |
| <i>Table 2 - Output Status Register</i> | 33 |
| <i>Table 3 - Command Status Register</i> | 34 |
| <i>Table 4 - Alibi Status Register</i> | 34 |
| <i>Table 5 - Filter</i> | 35 |
| <i>Table 7 - Input Functions</i> | 35 |
| <i>Table 6 - Zero Tracking</i> | 35 |
| <i>Table 8 - Output Functions</i> | 35 |
| Command Sending (Output Area) | 36 |
| Available Commands | 37 |
| Transmitter Configuration Via Fieldbus | 38 |
| Theoretical Calibration | 38 |
| Calibration | 39 |
| Calibration Linearization | 40 |
| Filter / Metric Parameters 1 | 41 |
| Metric Parameters 2 | 42 |
| Digital Inputs | 43 |
| Digital Output 1 | 44 |
| Digital Output 2 | 45 |
| Profinet Name | 46 |
| Scale Zeroing via Fieldbus | 47 |
| Mechanical Tare Zeroing via Fieldbus | 47 |
| Setup Backup and Restore via Fieldbus | 48 |
| Backup | 48 |
| Restore | 48 |
| Diagnostic Messages | 49 |

Introduction

Thank you for purchasing this product.

This manual contains fieldbus information for the following SCT-1SX digital weight transmitters:

- SCT-1SX-E/IP
- SCT-1SX-MODTCP
- SCT-1SX-PRONET

It is recommended that you carefully follow the instructions for programming the weight transmitter; performing actions not indicated in this manual could compromise the functionality of the scale.



Manuals are available from Rice Lake Weighing Systems at www.ricelake.com/manuals

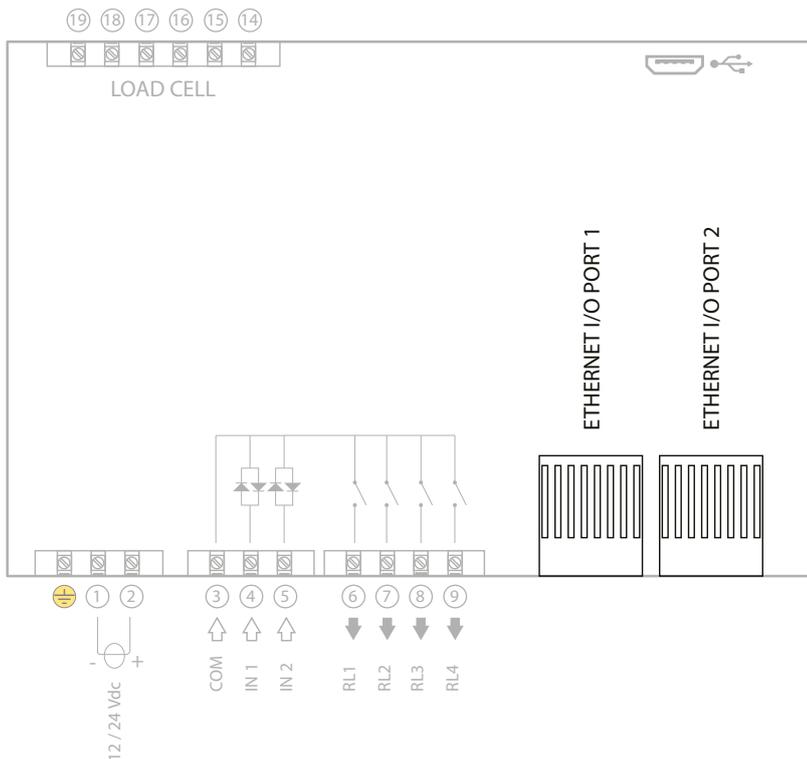
Warranty information is available at www.ricelake.com/warranties

Any problem with the product must be reported to the manufacturer or to the retailer where it was purchased.

Always TURN OFF THE POWER SUPPLY prior to installation or repair action.

Connection

SCT-1SX-E/IP, SCT-1SX-PRONET, SCT-1SX-MODTCP

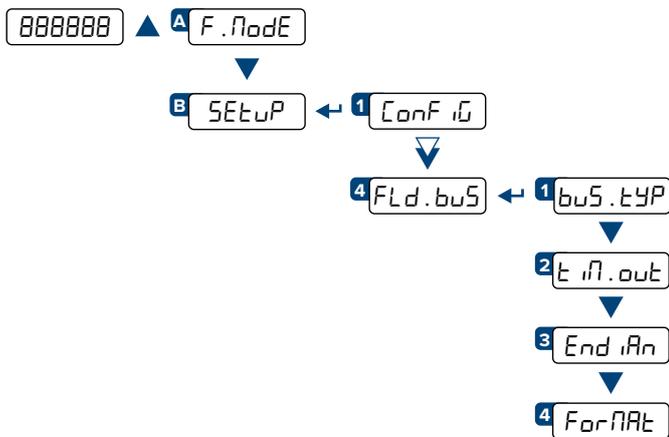


The connection to the Fieldbus goes through one of the two **ETHERNET** standard connectors of the device.

Fieldbus and Data Format Configuration

The Fieldbus can be set through the configuration menu, following the procedure below:

1. Access to the configuration menu:
 - Restart the device.
 - Press the key ▲ when `BBBBBB` is displayed.
2. Scroll the menu with the key ▼ until `SEtUP` is displayed and press ←.
3. Scroll the menu with the key ▼ until `FLd . buS` is displayed and press ←.
4. Selected the fieldbus type used and configure its parameters.



MENU OVERVIEW

`buS . tYP`

Depending on the selected Fieldbus, set the appropriate configuration parameters:

For Profinet:

| | |
|---|---------------------------|
| <code>ProF in</code> ← <code>AUt . CFg</code> | Dynamic IP configuration. |
| <code>iP . Add</code> | Static IP address. |
| <code>nEt . mSk</code> | Subnet mask. |
| <code>GAt . WAY</code> | Gateway. |

i The name of the Profinet node to use in the project linked to the network master node is **dini <IP4>**, <IP4> being the last Byte of the IP address incorporated in the device configuration, also when dynamic IP is used.
 Ex. IP - 192.168.1.10, the node name will be **dini-010**.
 If AUT.CFG parameter = YES, the IP address and Profinet name can be assigned directly from the network.

For Ethernet/IP:

| | | | |
|---------|---|-----------|---------------------------|
| Eth. IP | ← | Aut. CFG | Dynamic IP configuration. |
| | | IP. Add | Static IP address. |
| | | net. MSK | Subnet mask. |
| | | Gate. WAY | Gateway. |

For Modbus TCP:

| | | | |
|----------|---|-----------|---------------------------|
| Mod. TCP | ← | Aut. CFG | Dynamic IP configuration. |
| | | IP. Add | Static IP address. |
| | | net. MSK | Subnet mask. |
| | | Gate. WAY | Gateway. |

MENU OVERVIEW

Time.out End.iAn For.Fmt

| | | | |
|----------|---|-----|---|
| Time.out | ← | no | "Time out" error message displayed only once. |
| | | YES | "Time out" error message repeated. |

| | | | |
|---------|---|--------|----------------|
| End.iAn | ← | big | Big Endian. |
| | | Little | Little Endian. |

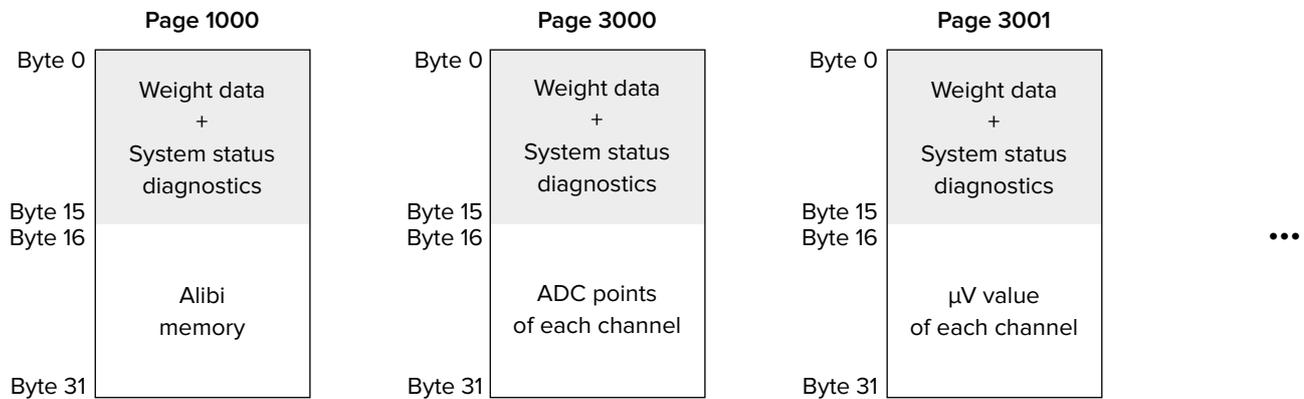
i This parameter changes the order of the data sent to and received from the PLC. If data is available but does not relate to data on the display, try changing this parameter.

| | | | |
|---------|---|---------|--|
| For.Fmt | ← | UNS.int | Unsigned integer (read the sign from Input status register). |
| | | FLoat | Float. |
| | | SIG.int | Signed integer. |

Data Reading (Input Area)

- The available data are divided into pages.
- To display data from pages 5xxx you must first send the command 35 (0x23) "LETTURA DATI".
- Depending on the Fieldbus, the data area size can be up to 128 Bytes.
- The size of each SCT-1SX page is 32 Bytes (therefore, even if the page size is 64 or 128 Bytes, only the first 32 available Bytes are used).
- The first 16 Bytes of each page always include the data concerning weight and weighing system status.
- Bytes 16 to 31 contain additional information, depending on the selected page (setup data, alibi memory etc.)
- The page selected by default is:
 - - 3001 (0x0BB9).
- In factory configuration the data format is Big Endian. To change the format, follow the procedure on page 6.
- Weight data are expressed with unsigned integers. (Es. 12,345 → 0x3039). To change it, follow the procedure at page 6.
- μ V and ADC points are always expressed with positive and negative integers. (Ex. -12,345 0xCFC7).

Model of the pages in the Input Area:



Available Pages

| Page | Name | Description | Read | Write |
|---|--|-------------|------|-------|
| 1000 (0x03E8) | Alibi memory | See page 9 | ● | |
| 3000 (0x0BB8) | ADC values | See page 10 | ● | |
| 3001 (0x0BB9) | µV values (*) | See page 11 | ● | |
| 5000 (0x1388) | Calibration 0 - Scale parameters | See page 12 | ● | ● |
| 5001 (0x1389) | Calibration 1 - Calibration points weights | See page 13 | ● | ● |
| 5002 (0x138A) | Calibration 2 - Calibration points ADC | See page 14 | ● | ● |
| 5003 (0x138B) | Calibration 3 - Legal state | See page 15 | ● | ● |
| 5004 (0x138C) | Calibration 4 - Filter and metrical parameters (1/2) | See page 16 | ● | ● |
| 5005 (0x138D) | Calibration 5 - Metrical parameters (2/2) | See page 17 | ● | ● |
| 5006 (0x138E) | Calibration 6 - Quick calibration | See page 18 | ● | ● |
| 5007 (0x138F) | Advanced filters | See page 19 | ● | ● |
| 5008 (0x1390) | Anti-peak filter | See page 20 | ● | ● |
| 5010 (0x1392) | Tare type | See page 21 | ● | ● |
| 5011 (0x1393) | Transmitter SN and firmware | See page 22 | ● | |
| 5015 (0x1397) | Unit of measure 2 ("COnUEr" mode) | See page 23 | | |
| 5030 (0x13A6) | Fieldbus configuration | See page 24 | ● | ● |
| 5031 (0x13A7) | Profinet name (only for SCT-1SX) | See page 25 | ● | ● |
| 5100 (0x13EC) | Inputs configuration | See page 26 | ● | ● |
| 5101 (0x13ED) ... 5104 (0x13F2) | Outputs configuration | See page 27 | ● | ● |
| 5110 (0x13F6) | Analog output configuration (1/3) | See page 28 | ● | ● |
| 5111 (0x13F7) | Analog output configuration (2/3) | See page 29 | ● | ● |
| 5112 (0x13F8) | Analog output configuration(3/3) | See page 30 | ● | ● |
| 6100 (0x17D4) | Setpoints values (1/2) | See page 31 | ● | |
| 6101 (0x17D5) | Setpoints values (2/2) | See page 32 | ● | |

(*) page selected by default at power-up.

Alibi Memory "Page 1000" (0x03E8)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|---|--|------------------|-------------------|---------------|---|
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B2 | H |
| 3 | | B0 | | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B2 | H |
| 7 | | B0 | | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | B1 | | |
| 16 | 30009 | B3 | H | Gross weight. | | | B0 | L |
| 17 | | B2 | | | | | B1 | |
| 18 | 30010 | B1 | L | | | | B2 | H |
| 19 | | B0 | | | | | B3 | |
| 20 | 30011 | B3 | H | Tare weight. | | | B0 | L |
| 21 | | B2 | | | | | B1 | |
| 22 | 30012 | B1 | L | | | | B2 | H |
| 23 | | B0 | | | | | B3 | |
| 24 | 30013 | B3 | H | ID | | | B0 | L |
| 25 | | B2 | | | | | B1 | |
| 26 | 30014 | B1 | L | | | | B2 | H |
| 27 | | B0 | | | | | B3 | |
| 28 | 30015 | B1 | - | Alibi status register | | | B0 | - |
| 29 | | B0 | | | | | B1 | |
| 30 | 30016 | - | - | Not used. | | | - | - |
| 31 | | - | | | | | - | |

ADC Value "Page 3000" (0x0BB8)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|--------------------------------|-------------------|---------------|----|
| | | B3 | B2 | B1 | B0 | B3 | B2 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer 10 = float | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | | | | |
| 16 | 30009 | B3 | H | ADC points. | | | B0 | L |
| 17 | | B2 | | | | | B1 | |
| 18 | 30010 | B1 | L | | | | B0 | H |
| 19 | | B0 | | | | | | |
| 20 | 30011 | - | - | Not used. | | | - | - |
| ... | ... | - | - | | | | | |
| 31 | 30016 | - | - | | | | | |

µV Value "Page 3001" (0x0BB9)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | | |
| 16 | 30009 | B1 | - | µV value. | | | B0 | - |
| 17 | | B0 | | | | | | |
| 18 | 30010 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 31 | 30016 | | | | | | | |

Calibration 0 - Scale Parameters "Page 5000" (0x1388)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|----|
| | | B3 | B2 | B1 | B0 | B3 | B2 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | | |
| 16 | 30009 | B3 | - | Unit of measure | 0 = g | 1 = kg | B0 | L |
| 17 | | B2 | | | 2 = t | 3 = lb | B1 | |
| 18 | 30010 | B1 | - | Range 1 division | | | B2 | H |
| 19 | | B0 | | | | | | |
| 20 | 30011 | B3 | - | Range 2 division | | | B0 | L |
| 21 | | B2 | | | | | | |
| 22 | 30012 | B1 | - | Decimals | | | B2 | H |
| 23 | | B0 | | | | | | |
| 24 | 30013 | B3 | H | Range 1 | | | B0 | L |
| 25 | | B2 | | | | | B1 | |
| 26 | 30014 | B1 | L | | | | B0 | H |
| 27 | | B0 | | | | | | |
| 28 | 30015 | B3 | H | Range 2 | | | B0 | L |
| 29 | | B2 | | | | | B1 | |
| 30 | 30016 | B1 | L | | | | B0 | H |
| 31 | | B0 | | | | | | |

To set the data, write the same positions in the output area and use command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 equals to 5000.

Calibration 1 - Calibration Points Weights "Page 5001" (0x1389)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|---|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | | |
| 16 | 30009 | B1 | - | Number of calibration points. | | | B0 | - |
| 17 | | B0 | | | | | | |
| 18 | 30010 | B1 | - | Sample weight 1. | | | B0 | L |
| 19 | | B0 | | | | | B1 | |
| 20 | 30011 | B1 | - | | | | B0 | H |
| 21 | | B0 | | | | | | |
| 22 | 30012 | B1 | - | Sample weight 2. | | | B0 | L |
| 23 | | B0 | | | | | B1 | |
| 24 | 30013 | B1 | - | | | | B0 | H |
| 25 | | B0 | | | | | | |
| 26 | 30014 | B1 | - | Sample weight 3. | | | B0 | L |
| 27 | | B0 | | | | | B1 | |
| 28 | 30015 | B1 | - | | | | B0 | H |
| 29 | | B0 | | | | | | |
| 30 | 30016 | B1 | - | Calibration state (same as page 5006, only reading) | | | B0 | - |
| 31 | | B0 | | | | | | |

To set the data, write the same positions in the output area and use command **36** (0x24) "DATA WRITING AND STORAGE" with PARAMETER 1 equals to 5001.

Calibration 2 - Calibration Points ADC "Page 5002" (0x138A)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|---|--|------------------|-------------------|---------------|---|
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B2 | H |
| 3 | | B0 | | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B2 | H |
| 7 | | B0 | | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | B0 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | B1 | | |
| 16 | 30009 | B3 | H | ADC value of the zero point. | | | B0 | L |
| 17 | | B2 | | | | | B1 | |
| 18 | 30010 | B1 | L | | | | B2 | H |
| 19 | | B0 | | | | | B3 | |
| 20 | 30011 | B3 | H | ADC value of the point 1. | | | B0 | L |
| 21 | | B2 | | | | | B1 | |
| 22 | 30012 | B1 | L | | | | B2 | H |
| 23 | | B0 | | | | | B3 | |
| 24 | 30013 | B3 | H | ADC value of the point 2. | | | B0 | L |
| 25 | | B2 | | | | | B1 | |
| 26 | 30014 | B1 | L | | | | B2 | H |
| 27 | | B0 | | | | | B3 | |
| 28 | 30015 | B3 | H | ADC value of the point 3. | | | B0 | L |
| 29 | | B2 | | | | | B1 | |
| 30 | 30016 | B1 | L | | | | B2 | H |
| 31 | | B0 | | | | | B3 | |

To set the data, write them to the same position in the output area and use command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 equal to 5002.

Calibration 3 - Legal State "Page 5003" (0x138B)

| Byte | Modbus TCP Register | Big Endian | | Dato | | Little Endian | |
|------|---------------------|------------|----|--|---|---------------|----|
| | | B3 | B2 | B1 | B0 | B0 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | B0 | L |
| 1 | | B2 | | | | B1 | |
| 2 | 30002 | B1 | L | | | B2 | H |
| 3 | | B0 | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | B0 | L |
| 5 | | B2 | | | | B1 | |
| 6 | 30004 | B1 | L | | | B2 | H |
| 7 | | B0 | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | B1 | - |
| 9 | | B0 | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | B0 | - |
| 11 | | B0 | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | B0 | - |
| 13 | | B0 | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 01 = sig. integer 10 = float | B0 | - |
| 15 | | B0 | | | | B1 | |
| 16 | 30009 | | - | Not used in reading. | | | - |
| 17 | | | | | | | |
| 18 | 30010 | | | | | | |
| 19 | | | | | | | |
| 20 | 30011 | B1 | - | Pre-calibration state | 0 = no. 1 = yes. | B0 | - |
| 21 | | B0 | | | | B1 | |
| 22 | 30012 | B1 | - | Setup size | | B0 | - |
| 23 | | B0 | | | | B1 | |
| 24 | 30013 | B1 | - | Restricted | 0 = internal use. 1 = restricted. | B0 | - |
| 25 | | B0 | | | | B1 | |
| 26 | 30014 | | - | Not used. | | | - |
| ... | ... | | | | | | |
| 31 | 30016 | | | | | | |

To set the data, write the same positions in the output area and use command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 equals to 5003.
The instrument will permanently save the setting and reboot.

Calibration 4 - Filter and Metrical Parameters (1/2) "Page 5004" (0x138C)

| Byte | Modbus TCP Register | Big Endian | | Dato | | Little Endian | |
|------|---------------------|------------|----|--|--|---------------|----|
| | | B3 | B2 | B1 | B0 | B0 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | B0 | L |
| 1 | | B2 | | | | B1 | |
| 2 | 30002 | B1 | L | | | B2 | H |
| 3 | | B0 | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | B0 | L |
| 5 | | B2 | | | | B1 | |
| 6 | 30004 | B1 | L | | | B2 | H |
| 7 | | B0 | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | B1 | - |
| 9 | | B0 | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | B0 | - |
| 11 | | B0 | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | B0 | - |
| 13 | | B0 | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer 01 = sig. integer 10 = float | B0 | - |
| 15 | | B0 | | | | B1 | |
| 16 | 30009 | B1 | - | Filter index (see Table 5 page 35) | | B0 | - |
| 17 | | B0 | | | | B1 | |
| 18 | 30010 | B1 | - | Rate custom filter. | | B0 | - |
| 19 | | B0 | | | | B1 | |
| 20 | 30011 | B1 | - | Win custom filter. | | B0 | - |
| 21 | | B0 | | | | B1 | |
| 22 | 30012 | B1 | - | Avg custom filter. | | B0 | - |
| 23 | | B0 | | | | B1 | |
| 24 | 30013 | B1 | - | Pit custom filter. | | B0 | - |
| 25 | | B0 | | | | B1 | |
| 26 | 30014 | B1 | - | Auto zero at start-up. | | B0 | - |
| 27 | | B0 | | | | B1 | |
| 28 | 30015 | B1 | - | Auto zero percentage. | | B0 | - |
| 29 | | B0 | | | | B1 | |
| 30 | 30016 | B1 | - | Zero percentage (by key / command) | | B0 | - |
| 31 | | B0 | | | | B1 | |

To set the data, write the same positions in the output area and use command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 equals to 5004.

Calibration 5 - Metrical Parameters (2/2) "Page 5005" (0x138D)

| Byte | Modbus TCP Register | Big Endian | | Dato | | Little Endian | |
|------|---------------------|------------|---|--|---|---------------|---|
| 0 | 30001 | B3 | H | Gross weight. | | B0 | L |
| 1 | | B2 | | | | B1 | |
| 2 | 30002 | B1 | L | | | B2 | H |
| 3 | | B0 | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | B0 | L |
| 5 | | B2 | | | | B1 | |
| 6 | 30004 | B1 | L | | | B2 | H |
| 7 | | B0 | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | B1 | - |
| 9 | | B0 | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | B0 | - |
| 11 | | B0 | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | B0 | - |
| 13 | | B0 | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 01 = sig. integer 10 = float | B0 | - |
| 15 | | B0 | | | | B1 | |
| 16 | 30009 | B1 | - | Zero tracking. | (see Table 6 page 35) | B0 | - |
| 17 | | B0 | | | | B1 | |
| 18 | 30010 | B1 | - | Division for stability. | (number of divisions) | B0 | - |
| 19 | | B0 | | | | B1 | |
| 20 | 30011 | B1 | - | G value of the calibration zone. | G value decimals – 9.7. | B0 | - |
| 21 | | B0 | | | | B1 | |
| 22 | 30012 | B1 | - | G value of the use zone. | E.g. g=9.80390, the value displayed will be 10390. | B0 | - |
| 23 | | B0 | | | | B1 | |
| 24 | 30013 | B1 | - | Zero tracking time. | (100-5000ms) | B0 | - |
| 25 | | B0 | | | | B1 | |
| 26 | 30014 | B1 | - | Stability detection time. | (10-10000ms) | B0 | - |
| 27 | | B0 | | | | B1 | |
| 28 | 30015 | B1 | - | Additional filter for stability detection. | (0-2000ms, 0 disabled) | B0 | - |
| 29 | | B0 | | | | B1 | |
| 30 | 30016 | B1 | - | Stability detection divisions. | (1-100 divisions) | B0 | - |
| 31 | | B0 | | | | B1 | |

To set the data, write the same positions in the output area and use command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 equals to 5005.

Calibration 6 - Condensed Calibration "Page 5006" (0x138E)

| Byte | Modbus TCP Register | Big Endian | | Dato | | Little Endian | |
|------|--|------------|----|--|-------------------------------------|-------------------|-------------------|
| | | B3 | B2 | B1 | B0 | B3 | B2 |
| 0 | 30001 | B3 | H | Gross weight. | | B0 | L |
| 1 | | B2 | | | | B1 | |
| 2 | 30002 | B1 | L | | | B2 | H |
| 3 | | B0 | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | B0 | L |
| 5 | | B2 | | | | B1 | |
| 6 | 30004 | B1 | L | | | B2 | H |
| 7 | | B0 | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | B1 | - |
| 9 | | B0 | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | B0 | - |
| 11 | | B0 | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 34). | | B0 | - |
| 13 | | B0 | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | Data format (bit 14 to 15) | 00 = uns. integer | 01 = sig. integer |
| 15 | | B0 | | | | 10 = float | |
| 16 | 30009 | B1 | - | Unit of measure. | 00 = g | 01 = kg | |
| 17 | | B0 | | | 10 = t | 11 = lb | |
| 18 | 30010 | B1 | - | Division. | | B0 | - |
| 19 | | B0 | | | | B1 | |
| 20 | 30011 | B1 | - | Number of decimals. | | B0 | - |
| 21 | | B0 | | | | B1 | |
| 22 | 30012 | B3 | H | Capacity. | | B0 | L |
| 23 | | B2 | | | | B1 | |
| 24 | 30013 | B1 | L | | | B2 | H |
| 25 | | B0 | | | | B3 | |
| 26 | 30014 | B3 | H | Sample weight for calibration. | | B0 | L |
| 27 | | B2 | | | | B1 | |
| 28 | 30015 | B1 | L | | | B2 | H |
| 29 | | B0 | | | | B3 | |
| 30 | 30016 | B1 | - | Calibration state (reading only) | 0 (0x00) = Calibration not started. | | B0 |
| 31 | | | | | 1 (0x01) = Acquisition in progress. | | |
| | | | | | 2 (0x02) = Acquisition OK. | | |
| | | | | | 3 (0x03) = Acquisition error. | | |
| | | | | | 4 (0x04) = Calibration OK. | | |
| 31 | | | | | 5 (0x05) = Calibration error. | | |
| | 6 (0x06) = Zero calibration in progress. | | | | | | |
| | | | | | | | B1 |

To set the data, write the same positions in the output area and use command **36 (0x24) "DATA WRITING AND STORAGE"** with PARAMETER 1 equals to 5006.

Automatically will be set:

Division 2 = 0, Range 2 = 0, Number of calibration points = 1, Sample weight 2 = 0, Sample weight 3 = 0, ADC value of the point 2 = 0, ADC value of the point 3 = 0.

Advanced Filters "Page 5007" (0x138F)

| Byte | Modbus TCP Register | Big Endian | | Dato | | Little Endian | |
|------|---------------------|------------|----|--|---|---------------|----|
| | | B3 | B2 | B1 | B0 | B0 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | B0 | L |
| 1 | | B2 | | | | B1 | |
| 2 | 30002 | B1 | L | | | B2 | H |
| 3 | | B0 | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | B0 | L |
| 5 | | B2 | | | | B1 | |
| 6 | 30004 | B1 | L | | | B2 | H |
| 7 | | B0 | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | B1 | - |
| 9 | | B0 | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | B0 | - |
| 11 | | B0 | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | B0 | - |
| 13 | | B0 | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 01 = sig. integer 10 = float | B0 | - |
| 15 | | B0 | | | | B1 | |
| 16 | 30009 | B1 | - | Filter 1 ID. | | B0 | - |
| 17 | | B0 | | | | B1 | |
| 18 | 30010 | B1 | - | Filter 1 value. | | B0 | - |
| 19 | | B0 | | | | B1 | |
| 20 | 30011 | B1 | - | Filter 2 ID. | | B0 | - |
| 21 | | B0 | | | | B1 | |
| 22 | 30012 | B1 | - | Filter 2 value. | | B0 | - |
| 23 | | B0 | | | | B1 | |
| 24 | 30013 | B1 | - | Filter 3 ID. | | B0 | - |
| 25 | | B0 | | | | B1 | |
| 26 | 30014 | B1 | - | Filter 3 value. | | B0 | - |
| 27 | | B0 | | | | B1 | |
| 28 | 30015 | - | - | Not used. | | - | - |
| ... | | | | | | | |
| 31 | 30016 | | | | | | |

| ID | Filter type | Value |
|----|-------------|---|
| 0 | - | Filter disabled. |
| 1 | Coarse | Frequency, 1 decimal (the value 30 stands for 3,0 Hz) |
| 4 | Selective | Frequency, 1 decimal (the value 500 stands for 50,0 Hz) |
| 5 | Fine | Percentage, 2 decimal (the value 100 stands for 10%) |

To set the data, write the same positions in the output area and use command **36** (0x24) "DATA WRITING AND STORAGE" with PARAMETER 1 equals to 5007.

Anti-Peak Filter "Page 5008" (0x139A)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | | |
| 16 | 30009 | B1 | - | Lock divisions (PF.LF.dU). | | | B0 | - |
| 17 | | B0 | | | | | | |
| 18 | 30010 | B1 | - | Unlocked to locked switch time (PF.LF.tE, 0,01 s). | | | B0 | - |
| 19 | | B0 | | | | | | |
| 20 | 30011 | B1 | - | Unlock divisions (PF.dU). | | | B0 | - |
| 21 | | B0 | | | | | | |
| 22 | 30012 | B1 | - | Locked band divisions (PF.bn.dU). | | | B0 | - |
| 23 | | B0 | | | | | | |
| 24 | 30013 | B1 | - | Locked peak time (PF.tPE, 0,01 s). | | | B0 | - |
| 25 | | B0 | | | | | | |
| 26 | 30014 | - | - | Not used. | | | - | - |
| ... | | - | - | | | | | |
| 31 | 30016 | - | - | | | | | |

To set the data, write the same positions in the output area and use command **36** (0x24) "DATA WRITING AND STORAGE" with PARAMETER 1 equals to 5008.

Tare Type "Page 5010" (0x1392)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | B0 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | B0 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | B0 | |
| 14 | 30008 | B1 | - | Selected page - Data format. (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | B1 | |
| 16 | 30009 | B1 | - | Tare type. | 0 = disabled | 1 = locked | B0 | - |
| 17 | | B0 | | | 2 = unlocked | B1 | | |
| 18 | 30010 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 21 | 30011 | | | | | | | |
| 22 | 30012 | B1 | - | Restore zero | | | B0 | - |
| 23 | | B0 | | | | | B1 | |
| 24 | 30013 | B1 | - | Restore tare | | | B0 | - |
| 25 | | B0 | | | | | B1 | |
| 26 | 30014 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 31 | 30016 | | | | | | | |

To set the data, write the same positions in the output area and use command **27** (0x1B) "SETUP WRITING" with PARAMETER 1 equals to 5010.

Transmitter SN and Firmware "Page 5011" (0x1393)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|---|--|------------------|-------------------|-----------------|---|
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B2 | H |
| 3 | | B0 | | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B2 | H |
| 7 | | B0 | | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | B0 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | (bit 14 to 15) | 10 = float | B1 | |
| 16 | 30009 | B1 | - | Hardware ID. | | | B0 | - |
| 17 | | B0 | | | | | B1 | |
| 18 | 30010 | B3 | H | Firmware version. | | | B0 | L |
| 19 | | B2 | | | | | B3: 0 | |
| 20 | 30011 | B1 | L | | | | B2 | H |
| 21 | | B0 | | | | | B2: release | |
| 22 | 30012 | B3 | H | SN. | | | B1 | L |
| 23 | | B2 | | | | | B1: sub-release | |
| 24 | 30013 | B1 | L | | | | B2 | H |
| 25 | | B0 | | | | | B0: bug-release | |
| 26 | 30014 | B1 | - | Legal Hardware ID. | | | B0 | L |
| 27 | | B0 | | Legal ID. | | | B1 | |
| 28 | 30015 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 31 | 30016 | | | | | | | |

Unit of Measure 2 ("ConUEr" mode) "Page 5015" (0x1397)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|---|-------------------------------|------------------|-------------------|----|
| | | B3 | B2 | B1 | B0 | B3 | B2 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B2 | H |
| 3 | | B0 | | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B2 | H |
| 7 | | B0 | | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | B0 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | Data format (bit 14 to 15) | 0 = uns. integer | 01 = sig. integer | |
| 15 | | B0 | | | | 10 = float | | |
| 16 | 30009 | B1 | - | Decimals of the unit of measure 2. | (0 to 4) | | | |
| 17 | | B0 | | | | | | |
| 18 | 30010 | B1 | - | Unit of measure 2. | 0 = default | | | |
| 19 | | B0 | | | 1 = custom | | | |
| 20 | 30011 | B1 | - | Division of the unit of measure 2. | (1, 2, 5, 10, 20, 50) | | | |
| 21 | | B0 | | | | | | |
| 22 | 30012 | B3 | H | Conversion factor of the unit of measure 2 (in fixed-point integer 5 decimal places). | | | B0 | L |
| 23 | | B2 | | | | | B1 | |
| 24 | 30013 | B1 | L | | | | B2 | H |
| 25 | | B0 | | | | | B3 | |
| 26 | 30014 | | | Not used. | | | | |
| 27 | | | | | | | | |
| 28 | 30015 | - | - | | | | - | - |
| 29 | | | | | | | | |
| 30 | 30016 | | | | | | | |
| 31 | | | | | | | | |

To set these data write them in the same positions in the output area and use command **27** (0x1B) "**WRITE SETUP**" with parameter 1 equal to 5015.

To make the changes permanent use command **28** (0x1C) "**SAVE SETUP**."

Fieldbus Configuration "Page 5030" (0x13A6)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|--------------------------------|-------------------|---------------|----|
| | | B3 | B2 | B1 | B0 | B3 | B2 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B2 | H |
| 3 | | B0 | | | | | B3 | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B2 | H |
| 7 | | B0 | | | | | B3 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 34). | | | B1 | - |
| 9 | | B0 | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 35). | | | B0 | - |
| 11 | | B0 | | | | | B1 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 34). | | | B0 | - |
| 13 | | B0 | | | | | B1 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 10 = float | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | | | B1 | |
| 16 | 30009 | B1 | - | Baud rate index. | | | B0 | - |
| 17 | | B0 | | | | | B1 | |
| 18 | 30010 | B3 | H | IP. | | | B0 | L |
| 19 | | B2 | | | | | B1 | |
| 20 | 30011 | B1 | L | | | | B2 | H |
| 21 | | B0 | | | | | B3 | |
| 22 | 30012 | B3 | H | Subnet mask. | | | B0 | L |
| 23 | | B2 | | | | | B1 | |
| 24 | 30013 | B1 | L | | | | B2 | H |
| 25 | | B0 | | | | | B3 | |
| 26 | 30014 | B3 | H | Gateway. | | | B0 | L |
| 27 | | B2 | | | | | B1 | |
| 28 | 30015 | B1 | L | | | | B2 | H |
| 29 | | B0 | | | | | B3 | |
| 30 | 30016 | B1 | - | Dynamic IP (*) / ID. | (*) | 0 = disabled | - | - |
| 31 | | B0 | | | | | 1 = enabled | |

| | Profibus | Devicenet | Canopen |
|-----------|----------|---|--|
| ID | 0 to 126 | 0 to 63 | 1 to 127 |
| Baud rate | - | 0: 500kBaud 1: 250kBaud 2: 125kBaud | 0: 1MBaud 1: 800kBaud 2: 500kBaud 3: 250kBaud 4: 125kBaud 5: 100kBaud 6: 50kBaud 7: 20kBaud 8: 10kBaud |

To set the data, write it in the same positions in the output area and use command **27** (0x1B) "SETUP WRITING" with PARAMETER 1 equal to 5030.

To activate the new parameters reboot the instrument with the command **34** (0x22) "REBOOT DEVICE".

Profinet Name (only for SCT-1SX-PRONET) "Page 5031" (0x13A7)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | | | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | B1 | | |
| 16 | 30009 | - | - | 1st Profinet name character (ASCII code). | | | - | - |
| 17 | | - | | 2nd Profinet name character (ASCII code). | | | - | |
| 18 | 30010 | - | - | 3rd Profinet name character (ASCII code). | | | - | - |
| 19 | | - | | 4th Profinet name character (ASCII code). | | | - | |
| 20 | 30011 | - | - | 5th Profinet name character (ASCII code). | | | - | - |
| 21 | | - | | 6th Profinet name character (ASCII code). | | | - | |
| 22 | 30012 | - | - | 7th Profinet name character (ASCII code). | | | - | - |
| 23 | | - | | 8th Profinet name character (ASCII code). | | | - | |
| 24 | 30013 | - | - | 9th Profinet name character (ASCII code). | | | - | - |
| 25 | | - | | 10th Profinet name character (ASCII code). | | | - | |
| 26 | 30014 | - | - | 11th Profinet name character (ASCII code). | | | - | - |
| 27 | | - | | 12th Profinet name character (ASCII code). | | | - | |
| 28 | 30015 | - | - | 13th Profinet name character (ASCII code). | | | - | - |
| 29 | | - | | 14th Profinet name character (ASCII code). | | | - | |
| 30 | 30016 | - | - | 15th Profinet name character (ASCII code). | | | - | - |
| 31 | | - | | 16th Profinet name character (ASCII code). | | | - | |

Allowed characters:

- a to z (lower case)
- 0 to 9
- symbol "-"

To write the parameters, use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equal to 5031.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

To activate the new parameters reboot the instrument with the command **34** (0x22) "**REBOOT DEVICE**".

Inputs Configuration "Page 5100" (0x13EC)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | | | |
| 16 | 30009 | B1 | - | Input 1 function (see table 7 page 35). | | | B0 | - |
| 17 | | B0 | | | | | | |
| 18 | 30010 | B1 | - | Input 2 function (see table 7 page 35). | | | B0 | - |
| 19 | | B0 | | | | | | |
| 20 | 30011 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 31 | 30016 | | | | | | | |

To set the data, write the same positions in the output area and use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equals to 5100.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

Outputs Configuration "Pages 5101 - 5104" (0x13ED - 13F0)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | | |
|------|---------------------|------------|----|--|---|-------------------|---------------|----|----|
| | | B3 | B2 | B1 | B0 | B3 | B2 | B1 | B0 |
| 0 | 30001 | B3 | H | Gross weight. | | | | B0 | L |
| 1 | | B2 | | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | | B0 | H |
| 3 | | B0 | | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | | B0 | L |
| 5 | | B2 | | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | | B0 | H |
| 7 | | B0 | | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | | B1 | - |
| 9 | | B0 | | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | | B0 | - |
| 11 | | B0 | | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | | B0 | - |
| 13 | | B0 | | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 10 = float | 01 = sig. integer | | B0 | - |
| 15 | | B0 | | | | | | | |
| 16 | 30009 | B1 | - | Output function (see table 8 page 35). (*) | | | | B1 | - |
| 17 | | B0 | | | | | | | |
| 18 | 30010 | B1 | - | Contact type. (*) | 0 = Normally open 1 = Normally close | | | B0 | - |
| 19 | | B0 | | | | | | | |
| 20 | 30011 | B1 | - | Modo di attivazione. (*) | 0 = Direct 1 = At stability | | | B0 | - |
| 21 | | B0 | | | | | | | |
| 22 | 30012 | B1 | - | Hysteresis. (*) | 0 = Disabled 1 = Enabled | | | B0 | - |
| 23 | | B0 | | | | | | | |
| 24 | 30013 | B1 | - | Sign. (*) | 0 = Positive 1 = Negative | | | B1 | - |
| 25 | | B0 | | | | | | | |
| 26 | 30014 | B1 | - | Activation delay. (*) | value in 0,1 s (max. 1000) | | | B0 | - |
| 27 | | B0 | | | | | | | |
| 28 | 30015 | B1 | - | Activation time. (*) | value in 0,1 s (max. 1000) | | | B1 | - |
| 29 | | B0 | | | | | | | |
| 30 | 30016 | - | - | Not used. | | | | - | - |
| 31 | | - | | | | | | | |

(*)

- Page 5101 - Output 1
- Page 5102 - Output 2
- Page 5103 - Output 3
- Page 5104 - Output 4

To set the data, write the same positions in the output area and use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equals to 5101-5104.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

Analogue Output Configuration (1/3) "Page 5101" (0x13F6)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|----------------|-------------------|-------------------|----|
| | | B3 | B2 | B1 | B0 | | | B0 |
| 0 | 30001 | B3 | H | Gross weight. | | | | L |
| 1 | | B2 | | | | | | |
| 2 | 30002 | B1 | L | | | | | |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | | L |
| 5 | | B2 | | | | | | |
| 6 | 30004 | B1 | L | | | | | |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | (bit 14 to 15) | 0 = uns. integer | 01 = sig. integer | - |
| 15 | | B0 | | | | 10 = float | | |
| 16 | 30009 | B1 | - | Operative mode | | 0 = Gross weight. | | - |
| 17 | | B0 | | | | 1 = Net weight. | | |
| 18 | 30010 | - | - | Not used. | | | | - |
| ... | | | | | | | | |
| 21 | 30011 | | | | | | | |
| 22 | 30012 | B1 | - | DAC value relative to 0V. | | | | - |
| 23 | | B0 | | | | | | |
| 24 | 30013 | B1 | - | DAC value relative to 10 V. | | | | - |
| 25 | | B0 | | | | | | |
| 26 | 30014 | B1 | - | DAC value relative to 4 mA. | | | | - |
| 27 | | B0 | | | | | | |
| 28 | 30015 | B1 | - | DAC value relative to 20 mA. | | | | - |
| 29 | | B0 | | | | | | |
| 30 | 30016 | - | - | Not used. | | | | - |
| 31 | | | | | | | | |

To set the data, write the same positions in the output area and use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equals to 5110.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

Analogue Output Configuration (2/3) "Page 5102" (0x13F7)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|---|
| | | B3 | B2 | B1 | B0 | B0 | B1 | |
| 0 | 30001 | B3 | H | Gross weight. | | | B0 | L |
| 1 | | B2 | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | B0 | H |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | B0 | L |
| 5 | | B2 | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | B0 | H |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | B1 | - |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | B0 | - |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | B0 | - |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer | 01 = sig. integer | B0 | - |
| 15 | | B0 | | | 10 = float | B1 | | |
| 16 | 3009 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 19 | 30010 | | | | | | | |
| 20 | 30011 | B3 | H | Weight of the calibration point 1. | | | B0 | L |
| 21 | | B2 | | | | | B1 | |
| 22 | 30012 | B1 | L | | | | B0 | H |
| 23 | | B0 | | | | | | |
| 24 | 30013 | B1 | - | DAC value relative to calibration point 1. | | | B0 | - |
| 25 | | B0 | | | | | | |
| 26 | 30014 | - | - | Not used. | | | - | - |
| ... | | | | | | | | |
| 29 | 30015 | | | | | | | |
| 30 | 30016 | B1 | - | Current value of the analogue output (DAC). | | | B0 | - |
| 31 | | B0 | | | | | | |

To set the data, write the same positions in the output area and use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equals to 5111.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

Analogue Output Configuration (3/3) "Page 5102" (0x13F8)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | |
|------|---------------------|------------|----|--|--------------------------------|-------------------|---------------|----|
| | | B3 | B2 | B1 | B0 | | | B0 |
| 0 | 30001 | B3 | H | Gross weight. | | | | L |
| 1 | | B2 | | | | | | |
| 2 | 30002 | B1 | L | | | | | |
| 3 | | B0 | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | L | |
| 5 | | B2 | | | | | | |
| 6 | 30004 | B1 | L | | | | | |
| 7 | | B0 | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | - | |
| 9 | | B0 | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | - | |
| 11 | | B0 | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | - | |
| 13 | | B0 | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) | 0 = uns. integer 10 = float | 01 = sig. integer | | |
| 15 | | B0 | | | | | | |
| 16 | 30009 | B3 | H | Weight of the calibration point 2. | | | L | |
| 17 | | B2 | | | | | | |
| 18 | 30010 | B1 | L | | | | | |
| 19 | | B0 | | | | | | |
| 20 | 30011 | B1 | - | DAC value relative to calibration point 2. | | | - | |
| 21 | | B0 | | | | | | |
| 22 | 30012 | B3 | H | Weight of the calibration point 3. | | | L | |
| 23 | | B2 | | | | | | |
| 24 | 30013 | B1 | L | | | | | |
| 25 | | B0 | | | | | | |
| 26 | 30014 | B1 | - | DAC value relative to calibration point 3. | | | - | |
| 27 | | B0 | | | | | | |
| 28 | 30015 | - | - | Not used. | | | - | |
| 29 | | - | | | | | | |
| 30 | 30016 | B1 | - | Current value of the analogue output (DAC). | | | - | |
| 31 | | B0 | | | | | | |

To set the data, write the same positions in the output area and use command **56** (0x38) "**SAVE PAGE**" with PARAMETER 1 equals to 512.

To make the changes permanent, send the command **28** (0x1C) "**SAVE SETUP**".

Setpoint Values (1/2) "Page 6100" (0x17D4)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | | |
|------|---------------------|------------|----|--|------------------|-------------------|---------------|------------|----|
| | | B3 | B2 | B1 | B0 | | | B0 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | | B0 | L |
| 1 | | B2 | | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | | B0 | L |
| 3 | | B0 | | | | | | B1 | |
| 4 | 30003 | B3 | H | Net weight. | | | | B0 | L |
| 5 | | B2 | | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | | B0 | L |
| 7 | | B0 | | | | | | B1 | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | | B1 | - |
| 9 | | B0 | | | | | | B0 | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | | B0 | - |
| 11 | | B0 | | | | | | B0 | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | | B0 | - |
| 13 | | B0 | | | | | | B0 | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer | 01 = sig. integer | | B0 | - |
| 15 | | B0 | | | | | | 10 = float | |
| 16 | 30009 | B3 | H | ON value Setpoint 1. | | | | B0 | L |
| 17 | | B2 | | | | | | B1 | |
| 18 | 30010 | B1 | L | | | | | B0 | H |
| 19 | | B0 | | | | | | B1 | |
| 20 | 30011 | B3 | H | OFF value Setpoint 1. | | | | B0 | L |
| 21 | | B2 | | | | | | B1 | |
| 22 | 30012 | B1 | L | | | | | B0 | H |
| 23 | | B0 | | | | | | B1 | |
| 24 | 30013 | B3 | H | ON value Setpoint 2. | | | | B0 | L |
| 25 | | B2 | | | | | | B1 | |
| 26 | 30014 | B1 | L | | | | | B0 | H |
| 27 | | B0 | | | | | | B1 | |
| 28 | 30015 | B3 | H | OFF value Setpoint 2. | | | | B0 | L |
| 29 | | B2 | | | | | | B1 | |
| 30 | 30016 | B1 | L | | | | | B0 | H |
| 31 | | B0 | | | | | | B1 | |

Integers or float data depending on the indicator configuration.

Setpoint Values (2/2) "Page 6101" (0x17D5)

| Byte | Modbus TCP Register | Big Endian | | Dato | | | Little Endian | | |
|------|---------------------|------------|----|--|--------------------------------|--------------------------------|-------------------|----|----|
| | | B3 | B2 | B1 | B0 | 0 = uns. integer 10 = float | 01 = sig. integer | B0 | B1 |
| 0 | 30001 | B3 | H | Gross weight. | | | | B0 | L |
| 1 | | B2 | | | | | | B1 | |
| 2 | 30002 | B1 | L | | | | | B0 | H |
| 3 | | B0 | | | | | | | |
| 4 | 30003 | B3 | H | Net weight. | | | | B0 | L |
| 5 | | B2 | | | | | | B1 | |
| 6 | 30004 | B1 | L | | | | | B0 | H |
| 7 | | B0 | | | | | | | |
| 8 | 30005 | B1 | - | Input Status Register (see Table 1 page 33). | | | | B1 | - |
| 9 | | B0 | | | | | | | |
| 10 | 30006 | B1 | - | Command Status Register (see Table 3 page 34). | | | | B0 | - |
| 11 | | B0 | | | | | | | |
| 12 | 30007 | B1 | - | Output Status Register (see Table 2 page 33). | | | | B0 | - |
| 13 | | B0 | | | | | | | |
| 14 | 30008 | B1 | - | Selected page - Data format (bit 0 to 13) (bit 14 to 15) | 0 = uns. integer 10 = float | 01 = sig. integer | | B0 | - |
| 15 | | B0 | | | | | | | |
| 16 | 30009 | B3 | H | ON value Setpoint 3. | | | | B0 | L |
| 17 | | B2 | | | | | | B1 | |
| 18 | 30010 | B1 | L | | | | | B0 | H |
| 19 | | B0 | | | | | | | |
| 20 | 30011 | B3 | H | OFF value Setpoint 3. | | | | B0 | L |
| 21 | | B2 | | | | | | B1 | |
| 22 | 30012 | B1 | L | | | | | B0 | H |
| 23 | | B0 | | | | | | | |
| 24 | 30013 | B3 | H | ON value Setpoint 4. | | | | B0 | L |
| 25 | | B2 | | | | | | B1 | |
| 26 | 30014 | B1 | L | | | | | B0 | H |
| 27 | | B0 | | | | | | | |
| 28 | 30015 | B3 | H | OFF value Setpoint 4. | | | | B0 | L |
| 29 | | B2 | | | | | | B1 | |
| 30 | 30016 | B1 | L | | | | | B0 | H |
| 31 | | B0 | | | | | | | |

Integers or float data depending on the indicator configuration.

Descriptive Charts

Table 1 - Input Status Register

(always Big Endian)

| Byte | | Modbus TCP Register | Bit | Description | Bit meaning | |
|------------|----|---------------------|-----|--------------------------|-------------|---------------|
| Big Endian | | | | | 0 | 1 |
| 8 | B1 | 30005 | 15 | Not used. | - | - |
| | | | 14 | | | |
| | | | 13 | | | |
| | | | 12 | Endian. | Big Endian | Little Endian |
| | | | 11 | Not used. | - | - |
| | | | 10 | | | |
| | | | 9 | Input 2. | Disabled | Enabled |
| | | | 8 | Input 1. | Disabled | Enabled |
| 9 | B0 | | 7 | Gross weight = 0. | No | Si |
| | | | 6 | Manual tare condition. | No | Si |
| | | | 5 | Inserted tare condition. | No | Si |
| | | | 4 | Overload condition. | No | Si |
| | | | 3 | Underload condition. | No | Si |
| | | | 2 | Weight stability. | No | Si |
| | | | 1 | Gross weight polarity. | + | - |
| | | | 0 | Net weight polarity. | + | - |

Table 2 - Output Status Register

| Byte | | ModbusTCP Register | Bit | Description | Bit meaning | |
|------------|----|--------------------|-----|-------------------------------|--|-----------|
| Big Endian | | | | | 0 | 1 |
| 12 | B1 | 30007 | 15 | Communication scale - Module. | Bit that changes every second if the communication between scale and module is active. | |
| | | | 14 | Decimals (B1). | 00 = 0 | 01 = 1 |
| | | | 13 | Decimals (B0). | 10 = 2 | 11 = 3 |
| | | | 12 | Not used. | - | - |
| | | | 11 | | | |
| | | | 10 | | | |
| | | | 9 | Not used. | - | - |
| | | | 8 | | | |
| 13 | B0 | | 7 | Unit of measure (B1) | 00 = g | 01 = kg |
| | | | 6 | Unit of measure (B0) | 10 = t | 11 = lb |
| | | | 5 | Not used. | - | - |
| | | | 4 | | | |
| | | | 3 | Relay 4. | Not energized | Energized |
| | | | 2 | Relay 3. | Not energized | Energized |
| | | | 1 | Relay 2. | Not energized | Energized |
| | | | 0 | Relay 1. | Not energized | Energized |

Table 3 - Command Status Register

| Byte | | Modbus TCP Register | Bit | Description | Bit meaning | | | | |
|------------|----|---------------------|---------|------------------------------|---------------------|---|--------------------------------------|--|--|
| Big Endian | | | | | | | | | |
| 10 | B1 | 30006 | 15 | Last command received. | | | | | |
| | | | 14 | | | | | | |
| | | | 13 | | | | | | |
| | | | 12 | | | | | | |
| | | | 11 | | | | | | |
| | | | 10 | | | | | | |
| | | | 9 | | | | | | |
| | | | 8 | | | | | | |
| 11 | B0 | 30006 | 7 (MSB) | Processed commands counting. | Value in module 16. | | | | |
| | | | 6 | | | | | | |
| | | | 5 | | | | | | |
| | | | 4 (LSB) | | | | | | |
| | | | | | | 3 | Result of the last command received: | 0000 = Correct and performed command. 0001 = Incorrect command. 0010 = Incorrect data in command. 0011 = Command not allowed. 0100 = Non-existent command. | |
| | | | | | | 2 | | | |
| | | | | | | 1 | | | |
| | | | | | | 0 | | | |

Table 4 - Alibi Status Register

| Byte | | Modbus TCP Register | Bit | Description | Bit meaning | | | | | | | |
|------------|----|---------------------|-----|-------------------|----------------------|----|------------|---------------|---------------|---------|--|----|
| Big Endian | | | | | 0 | 1 | | | | | | |
| 28 | B1 | 30015 | 15 | Not used. | | | | | | | | |
| | | | 14 | | | | | | | | | |
| | | | 13 | | | | | | | | | |
| | | | 12 | | | | | | | | | |
| | | | | | | 11 | Tare type. | Semiautomatic | Manual | | | |
| | | | | | | | | | Scale number. | 1 to 4. | | |
| | | | | | | | | | | | | 10 |
| | | | | | | | | | | | | 9 |
| 8 | | | | | | | | | | | | |
| 29 | B0 | 30015 | 7 | Rewriting number. | 0 to 255 rewritings. | | | | | | | |
| | | | 6 | | | | | | | | | |
| | | | 5 | | | | | | | | | |
| | | | 4 | | | | | | | | | |
| | | | 3 | | | | | | | | | |
| | | | 2 | | | | | | | | | |
| | | | 1 | | | | | | | | | |
| | | | 0 | | | | | | | | | |

Table 5 - Filter

| Index | Filter | Description |
|-----------|--------|--|
| 0 (0x00) | F 1 | 5 Hz filter |
| 1 (0x01) | F 2 | 10 Hz filter |
| 2 (0x02) | F 3 | 20 Hz filter |
| 3 (0x03) | F 4 | 40 Hz filter |
| 4 (0x04) | F 5 | 80 Hz filter |
| 5 (0x05) | F 6 | 160 Hz filter |
| 6 (0x06) | F 7 | 325 Hz filter |
| 7 (0x07) | F 8 | 650 Hz filter (*) |
| 8 (0x08) | F 9 | 1300 Hz filter (*) |
| 9 (0x09) | F 10 | 2600 Hz filter (*) |
| 10 (0x0A) | F 11 | 4800 Hz filter (*) |
| 11 (0x0B) | CUSTOM | Custom filter (for manufacturer's use only). |

(*) Available only on SCT1SX models.

Table 6 - Zero Tracking

| Value | Meaning |
|-----------|-----------------|
| 0 (0x00) | Disabled. |
| 1 (0x01) | 1 / 4 Division. |
| 2 (0x02) | 1 / 2 Division. |
| 4 (0x04) | 1 Division. |
| 8 (0x08) | 2 Divisions. |
| 16 (0x10) | 4 Divisions. |
| 24 (0x18) | 6 Divisions. |
| 32 (0x20) | 8 Divisions. |
| 40 (0x28) | 10 Divisions. |

Table 7 - Input Functions

| Value | Meaning |
|----------|------------------------|
| 0 (0x00) | No function. |
| 1 (0x01) | Pression of Zero key. |
| 2 (0x02) | Pression of Tare key. |
| 3 (0x03) | Pression of Mode key. |
| 4 (0x04) | Pression of Print key. |
| 5 (0x05) | Pression of C key. |
| 6 (0x06) | Off. |
| 7 (0x07) | Disabled keyboard. |

Table 8 - Output Functions

| Value | Meaning |
|-----------|---|
| 0 (0x00) | No function. |
| 1 (0x01) | Setpoint on gross weight. |
| 2 (0x02) | Setpoint on net weight. |
| 4 (0x04) | Gross weight = 0. |
| 5 (0x05) | Net weight = 0. |
| 6 (0x06) | Unstable weight. |
| 23 (0x17) | Print key pressed. |
| 25 (0x19) | Mode key pressed. |
| 26 (0x1A) | C key pressed. |
| 27 (0x1B) | Zero key pressed. |
| 28 (0x1C) | Tare key pressed. |
| 29 (0x1D) | Error. |
| 30 (0x1E) | Setpoint on gross weight if a tare is active. |

Command Sending (Output Area)

- Commands are sent in the first 14 Bytes of the Output Area.
- Some commands need specific parameters.
- In the first 2 Bytes the command is specified, in Bytes 2 to 5 PARAMETER 1 is specified, in Bytes 6 to 9 PARAMETER 2 is specified, in Bytes 10 to 13 PARAMETER 3 is specified.
- Depending on the Fieldbus, the page size can reach 128 Bytes.
- Each SCT-1SX page size is 32 Bytes (therefore, even if the page size is 128 Bytes, only the first 32 available Bytes are used).
- Only the first 10 Bytes of each page are used to send commands.
- The last 16 Bytes are used to write data.
- Data are expressed by default in Big Endian format. To modify the format follow the procedure at page 6.

How to Send a Command

1. If required by the command, insert the required parameters in Bytes 2 to 13.
2. Write the command in Byte 1. The execution of the command occurs when the content in Byte 1 changes.

WARNING: Byte 0 value must equal 0 (0x00).

| Byte | Modbus TCP Register | Big Endian | | Data | Little Endian | |
|------|---------------------|------------|---|--|---------------|---|
| 0 | 40001 | B1 | - | 0 (0x00) always zero. | B0 | - |
| 1 | | B0 | | Command (see command list at page 38). | B1 | |
| 2 | 40002 | B3 | H | Parameter 1. | B0 | L |
| 3 | | B2 | | | B1 | |
| 4 | 40003 | B1 | L | | B2 | H |
| 5 | | B0 | | | B3 | |
| 6 | 40004 | B3 | H | Parameter 2. | B0 | L |
| 7 | | B2 | | | B1 | |
| 8 | 40005 | B1 | L | | B2 | H |
| 9 | | B0 | | | B3 | |
| 10 | 40006 | B3 | H | Parameter 3. | B0 | L |
| 11 | | B2 | | | B1 | |
| 12 | 40007 | B1 | L | | B2 | H |
| 13 | | B0 | | | B3 | |
| 14 | 40008 | B1 | - | Command counter. | B0 | - |
| 15 | | B0 | | | B1 | |

Available Commands

| COMMAND | DESCRIPTION | PARAMETER 1 | PARAMETER 2 |
|------------------|--|---|---|
| 0 (0x00) | No commands. | <i>Use this command before repeating the same command twice.</i> | |
| 1 (0x01) | Zero. | - | - |
| 2 (0x02) | Tare. | - | - |
| 3 (0x03) | Manual tare. | Tare value. | - |
| 10 (0x0A) | Writing setpoint 1. | "Threshold" weight for output activation. | "Threshold" weight for output deactivation. |
| 11 (0x0B) | Writing setpoint 2. | "Threshold" weight for output activation. | "Threshold" weight for output deactivation. |
| 12 (0x0C) | Writing setpoint 3. | "Threshold" weight for output activation. | "Threshold" weight for output deactivation. |
| 13 (0x0D) | Writing setpoint 4. | "Threshold" weight for output activation. | "Threshold" weight for output deactivation. |
| 25 (0x19) | Set relay status. (relays must have function: 0 "no function"). | Bitmask of relays status to be enabled (<i>bit 0 = relay 1, bit 1 = relay 2 bit 2 = relay 3, bit 3 = relay 4</i>). | Always 0 (0x00). |
| 26 (0x1A) | Setup reading. | Setup page to read 0 to 63 (0x00 to 0x3F). | - |
| 27 (0x1B) | Setup writing. | Setup page to write 0 to 63 (0x00 to 0x3F). | - |
| 28 (0x1C) | Save setup. | - | - |
| 29 (0x1D) | Change page. | Destination page. | - |
| 30 (0x1E) | Alibi memory reading. | Rewriting number. | Weight alibi ID. |
| 31 (0x1F) | Weight storage in alibi memory. | - | - |
| 34 (0x22) | Reboot device. | - | - |
| 35 (0x23) | Data reading. | - | - |
| 36 (0x24) | Data writing and storage. | Parameter 1 = 0 (0x00) to store data. Parameter 1 = 500X (0x138x) for page writing. | - |
| 37 (0x25) | Calibration point acquisition. | 0 (0x00) = Zero point 1 (0x01) = First point 2 (0x02) = Second point 3 (0x03) = Third point. | - |
| 38 (0x26) | Cancel ongoing calibration. | - | - |
| 39 (0x27) | Zero calibration. | - | - |
| 40 (0x28) | Enable / disable keypad. | 1 (0x01): Enable keypad. 0 (0x00): Disable keypad. | - |
| 55 (0x37) | Disable a peripheral device. | 0 (0x00) = disables digital outputs (parameter 2). 1 (0x01) = disables analog output (parameter 2). | Bit 0 = 1 disables relay 1 / analog output. Bit 1 = 1 disables relay 2. |
| 56 (0x38) | Save page. | Page to save. | - |
| 59 (0x3B) | Data format setting. | 0 (0x00) = Big Endian. 1 (0x01) = Little Endian. | - |
| 63 (0x3F) | Data type setting. | 0 (0x00) = Unsigned integer 1 (0x01) = Signed integer 2 (0x02) = Float | - |
| 66 (0x42) | Theoretical calibration. | See par. "Theoretical calibration" | |

Transmitter Configuration Via Fieldbus

PROCEDURE

1. Send the command **35** (0x23) "**DATA READING**".
2. Write the Bytes from 16 to 31 of the exit area of the page containing the desired parameter(s).
NOTA: All 16 Bytes are always written, so you must enter the values for all parameters.
3. Save the page that contains the modified parameter.
Use the commands specified below the table that contains the parameter(s).
4. Store the configuration.
Use the commands specified below the table that contains the parameter(s).

Theoretical Calibration

1. Write parameters registers:
 Byte 2 to 5 (PARAMETER 1): total load cells capacity. Scale decimals.
 Byte 6 to 9 (PARAMETER 2): load cells sensitivity (*). 5 decimals.
 Byte 10 to 13 (PARAMETER 3): mechanical tare value (if not known, insert the value 0). Scale decimals + 1.
2. Send the command **66** (0x42) "**THEORETICAL CALIBRATION**".
3. Save the parameters by sending the command **28** (0x1C) "**SAVE SETUP**".



If there are several load cells connected via a junction/equalisation box, enter the average value:

$$\frac{(mV/V \text{ cell 1}) + (mV/V \text{ cell 2}) + (mV/V \text{ cell 3}) + \dots + (mV/V \text{ cell n})}{n}$$

Example:

Theoretical calibration of a platform with 4 load cells.

Total capacity = 2000kg

Mechanical tare = 55 kg

Load cells sensitivity: cell 1 = 2,01032

cell 2 = 1,99420

cell 3 = 1,98846

cell 4 = 2,00375

| Byte | Modbus TCP Register | Big Endian | | Data | Little Endian | |
|------|---------------------|------------|----|-----------------------|---------------|----|
| | | B3 | B2 | | B0 | B1 |
| 0 | 40001 | B1 | - | 0 (0x00) always zero. | B0 | - |
| 1 | | B0 | - | 66 (0x42) | B1 | - |
| 2 | 40002 | B3 | H | 2000 (0x07D0) | B0 | L |
| 3 | | B2 | H | | B1 | L |
| 4 | 40003 | B1 | L | | B2 | H |
| 5 | | B0 | L | | B3 | H |
| 6 | 40004 | B3 | H | 199918 (0x00030CEE) | B0 | L |
| 7 | | B2 | H | | B1 | L |
| 8 | 40005 | B1 | L | | B2 | H |
| 9 | | B0 | L | | B3 | H |
| 10 | 40006 | B3 | H | 550 (0x0226) | B0 | L |
| 11 | | B2 | H | | B1 | L |
| 12 | 40007 | B1 | L | | B2 | H |
| 13 | | B0 | L | | B3 | H |

Calibration

1. Send command **35** (0x23) "**DATA READING**".

2. Modify required parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|---------------------|-------------------|-----------------|------|---------------------|------------|---|---------------|---|
| Description | Possible values | | | | | | | |
| Unit of measure. | 0 = kg 1 = g | 2 = t 3 = lb | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | | B1 | |
| Resolution. | 1, 2, 5. | | 18 | 40010 | B1 | - | B0 | - |
| | | | 19 | | B0 | | B1 | |
| Decimal places. | 0, 1, 2, 3, 4, 5. | | 20 | 40011 | B1 | - | B0 | - |
| | | | 21 | | B0 | | B1 | |
| Capacity. | From 1 to 999999. | | 22 | 40012 | B3 | H | B0 | L |
| | | | 23 | | B2 | | B1 | |
| | | | 24 | 40013 | B1 | L | B2 | H |
| | | | 25 | | B0 | | B3 | |
| Calibration weight. | From 1 to 999999. | | 26 | 40014 | B3 | H | B0 | L |
| | | | 27 | | B2 | | B1 | |
| | | | 28 | 40015 | B1 | L | B2 | H |
| | | | 29 | | B0 | | B3 | |

3. Save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5006** (0x138E) and send the command **36** (0x24) "**DATA WRITING AND STORAGE**".

4. Acquire calibration points:

- Unload the scale. Write in Bytes 2 to 5 (PARAMETER 1) the value 0 (0x00) and send the command **37** (0x25) "**CALIBRATION POINT ACQUISITION**".
- Check that in Byte 30 and 31 the value is equal to 2 (Acquisition OK).
- Load the scale with the sample weight. Write in Bytes 2 to 5 (PARAMETER 1) the value 1 (0x01) and increase the command counter value (Byte 15).
- Check that in Byte 30 and 31 the value is equal to 4 (Acquisition OK).

5. Send the command **36** (0x24) "**DATA WRITING AND STORAGE**" with PARAMETER 1 = 0 (0x00) to save the calibration.

- Check that in Byte 30 and 31 the value is equal to 4 (Calibration OK).

Calibration Linearization

1. Send the command **35** (0X23) "DATA READING".

2. Modify required parameters:

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|---------------------------|--|------------------|------|---------------------|------------|----|---------------|----|
| Description | Possible values ₁₀ | | | | B1 | B0 | B3 | B2 |
| Calibration point number. | 1, 2, 3. | 5001 (0x1389) | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | - | B1 | - |
| Calibration weight 1. | From 1 to 999999. | | 18 | 40010 | B3 | H | B0 | L |
| | | | 19 | | B2 | H | B1 | L |
| | | | 20 | 40011 | B1 | L | B2 | H |
| | | | 21 | | B0 | L | B3 | H |
| Calibration weight 2. | From weight calibration value 1 to 999999. | | 22 | 40012 | B3 | H | B0 | L |
| | | | 23 | | B2 | H | B1 | L |
| | | | 24 | 40013 | B1 | L | B2 | H |
| | | | 25 | | B0 | L | B3 | H |
| Calibration weight 3. | From calibration weight 2 to 999999. | | 26 | 40014 | B3 | H | B0 | L |
| | | | 27 | | B2 | H | B1 | L |
| | | | 28 | 40015 | B1 | L | B2 | H |
| | | | 29 | | B0 | L | B3 | H |

3. Save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5001** (0x1389) and send the command **36** (0x24) "DATA WRITING AND STORAGE".

4. Acquire calibration points:

- Unload the scale. Write in Bytes 2 to 5 (PARAMETER 1) the value 0 (0x00) and send the command **37** (0x25) "CALIBRATION POINT ACQUISITION".
- Check that in Byte 30 and 31 the value is equal to 2 (Acquisition OK).
- Load the scale with the first sample weight. Write in Bytes 2 to 5 (PARAMETER 1) the value 1 (0x01) and increase the command counter value (Byte 15).
- Check that in Byte 30 and 31 the value is equal to 4 (Acquisition OK).
- Load the scale with the second sample weight. Write in Bytes 2 to 5 (PARAMETER 1) the value 1 (0x01) and increase the command counter value (Byte 15).
- Check that in Byte 30 and 31 the value is equal to 4 (Acquisition OK).
- Load the scale with the third sample weight. Write in Bytes 2 to 5 (PARAMETER 1) the value 1 (0x01) and increase the command counter value (Byte 15).
- Check that in Byte 30 and 31 the value is equal to 4 (Calibration OK).

5. Send the command **36** (0x24) "DATA WRITING AND STORAGE" with PARAMETER 1 = 0 (0x00) to save the calibration.

Filter / Metric Parameters 1

1. Send the command **35** (0x23) "DATA READING".

2. Modify required parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | | | |
|--------------------------------------|--|-------------------------|---------------------------|-------------------------------|------------|-------|---------------|---|----|---|
| Description | Possible values ₁₀ | | | | | | | | | |
| Filter index. | From 0 to 12 (see table 5 page 34). | 5004 (0x138C) | 16 | 40009 | B1 | - | B0 | - | | |
| | | | 17 | | B0 | | B1 | | | |
| Custom filter. | For manufacturer's use only. | | 18 | 40010 | B1 | - | B0 | - | | |
| | | | 19 | | B0 | | B1 | | | |
| | | | 20 | 40011 | B1 | - | B0 | - | | |
| | | | 21 | | B0 | | B1 | | | |
| | | | 22 | 40012 | B1 | - | B0 | - | | |
| | | | 23 | | B0 | | B1 | | | |
| | | | 24 | 40013 | B1 | - | B0 | - | | |
| | | | 25 | | B0 | | B1 | | | |
| | | | Auto-zeroing at power-up. | 0 = Disabled. 1 = Enabled. | 26 | 40014 | B1 | - | B0 | - |
| | | | | | 27 | | B0 | | B1 | |
| Auto-zeroing percentage at power-up. | From 0 to 50. From 0 to 10 (<i>approved version</i>). | 28 | 40015 | B1 | - | B0 | - | | | |
| | | 29 | | B0 | | B1 | | | | |
| Zero percentage by key / command. | Da 0 a 10. Da 0 a 2 (<i>approved version</i>). | 30 | 40016 | B1 | - | B0 | - | | | |
| | | 31 | | B0 | | B1 | | | | |

3. To save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5004** (0x138C) and send the command **36** (0x24) "DATA WRITING AND STORAGE".
- Write in Bytes 2 to 5 (PARAMETER 1) the value **0** (0x00) and increase the command counter value (Byte 15).

Metric Parameters 2

1. Send the command **35** (0x23) "DATA READING".

2. Modify the desired parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|--------------------------|--|------------------|------|---------------------|------------|---|---------------|---|
| Description | Possible values ₁₀ | | | | | | | |
| Zero tracking divisions. | See chart below. | 5005 (0x138D) | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | | B1 | |
| Divisions for stability. | 0 to 99. 0 to 2 (approved version). | | 18 | 40010 | B1 | - | B0 | - |
| | | | 19 | | B0 | | B1 | |
| "g" calibration zone. | See note below. | | 20 | 40011 | B1 | - | B0 | - |
| | | | 21 | | B0 | | B1 | |
| "g" area of use. | See note below. | | 22 | 40012 | B1 | - | B0 | - |
| | | | 23 | | B0 | | B1 | |

| VALUE | MEANING |
|-----------|-----------------|
| 0 (0x00) | Disabled. |
| 1 (0x01) | 1 / 4 Division. |
| 2 (0x02) | 1 / 2 Division. |
| 4 (0x04) | 1 Division. |
| 8 (0x08) | 2 Divisions. |
| 16 (0x10) | 4 Divisions. |
| 24 (0x18) | 6 Divisions. |
| 32 (0x20) | 8 Divisions. |
| 40 (0x28) | 10 Divisions. |



The value to insert is calculated by subtracting 9.7 from the gravity value and considering only decimal places.

Ex. for the gravity value 9.80390, insert **10390** / (0x2896).
 $9.80390 - 9.7 = 0.10390$.

3. To save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5005** (0x138D) and send the command **36** (0x24) "DATA WRITING AND STORAGE".
- Write Bytes 2 to 5 (PARAMETER 1) the value **0** (0x00) and increase the command counter value (Byte 15).

Digital Inputs

1. Write in Bytes 2 to 5 (PARAMETER 1) the value **5100** (0x13EC) and send the command **29** (0x1D) "**CHANGE PAGE**".

2. Modify the desired parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|-------------------|------------------|-------------------------|------|---------------------|------------|---|---------------|---|
| Description | Possible values | | | | | | | |
| Input 1 function. | See chart below. | 5100 (0x13EC) | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | | B1 | |
| Input 2 function. | See chart below. | | 18 | 40010 | B1 | - | B0 | - |
| | | | 19 | | B0 | | B1 | |

| VALUE | MEANING |
|-----------------|---------------------|
| 0 (0x00) | No function. |
| 1 (0x01) | Pressing Zero key. |
| 2 (0x02) | Pressing Tare key. |
| 3 (0x03) | Pressing Mode key. |
| 4 (0x04) | Pressing Print key. |
| 5 (0x05) | Pressing C key. |
| 6 (0x06) | Off. |
| 7 (0x07) | Keyboard disabling. |

3. To save parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5100** (0x13EC) and send the command **56** (0x38) "**SAVE PAGE**".
- Send command **28** (0x1C) "**SAVE SETUP**".

Digital Output 1

1. Write in Bytes 2 to 5 (PARAMETER 1) the value **5101** (0x13ED) and send the command **29** (0x1D) "**CHANGE PAGE**".

2. Modify the desired parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|-----------------------|--|-------------------------|-------|---------------------|------------|----|---------------|---|
| Description | Possible values | | | | | | | |
| Output function. | See chart below. | 5101 (0x13ED) | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | | B1 | |
| Contact type (NO/NC). | 0 (0x00) = Normally open. 1 (0x01) = Normally closed. | | 18 | 40010 | B1 | - | B0 | - |
| | | | 19 | | B0 | | B1 | |
| Switching condition. | 0 (0x00) = Direct. 1 (0x01) = At stability. | | 20 | 40011 | B1 | - | B0 | - |
| | | | 21 | | B0 | | B1 | |
| Hysteresis. | 0 (0x00) = Disabled. 1 (0x01) = Enabled. | | 22 | 40012 | B1 | - | B0 | - |
| | | | 23 | | B0 | | B1 | |
| Sign. | 0 (0x00) = Positive. 1 (0x01) = Negative. | | 24 | 40013 | B1 | - | B0 | - |
| | | | 25 | | B0 | | B1 | |
| Delayed switching. | 0 to 1000 (0x00 to 0x03E8) (in tenths of seconds). | 26 | 40014 | B1 | - | B0 | - | |
| | | 27 | | B0 | | B1 | | |
| Activation time. | 0 to 1000 (0x00 to 0x03E8) (in tenths of seconds). | 28 | 40015 | B1 | - | B0 | - | |
| | | 29 | | B0 | | B1 | | |

| VALUE | MEANING |
|------------------|---|
| 0 (0x00) | No function. |
| 1 (0x01) | Setpoint on gross weight. |
| 2 (0x02) | Setpoint on net weight. |
| 4 (0x04) | Gross weight at zero. |
| 5 (0x05) | Net weight at zero. |
| 6 (0x06) | Moving weight. |
| 23 (0x17) | Print key pressed. |
| 25 (0x19) | Mode key pressed. |
| 26 (0x1A) | C key pressed. |
| 27 (0x1B) | Zero key pressed. |
| 28 (0x1C) | Tare key pressed. |
| 29 (0x1D) | Error. |
| 30 (0x1E) | Setpoint in net weight if a tare was set. |

3. To save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5101** (0x13ED) and send the command **56** (0x38) "**SAVE PAGE**".
- Send the command **28** (0x1C) "**SAVE SETUP**".

Digital Output 2

1. Write in Bytes 2 to 5 (PARAMETER 1) the value **5102** (0x13EE) and send the command **29** (0x1D) "CHANGE PAGE".

2. Modify required parameters.

| Parameter | | Page | Byte | Modbus TCP Register | Big Endian | | Little Endian | |
|-----------------------|--|------------------|-------|---------------------|------------|----|---------------|---|
| Description | Possible values | | | | | | | |
| Output function. | See chart below. | 5102 (0x13EE) | 16 | 40009 | B1 | - | B0 | - |
| | | | 17 | | B0 | | B1 | |
| Contact type (NO/NC). | 0 (0x00) = Normally open. 1 (0x01) = Normally closed. | | 18 | 40010 | B1 | - | B0 | - |
| | | | 19 | | B0 | | B1 | |
| Switching condition. | 0 (0x00) = Direct. 1 (0x01) = At stability. | | 20 | 40011 | B1 | - | B0 | - |
| | | | 21 | | B0 | | B1 | |
| Hysteresis. | 0 (0x00) = Disabled. 1 (0x01) = Enabled. | | 22 | 40012 | B1 | - | B0 | - |
| | | | 23 | | B0 | | B1 | |
| Sign. | 0 (0x00) = Positive. 1 (0x01) = Negative. | | 24 | 40013 | B1 | - | B0 | - |
| | | | 25 | | B0 | | B1 | |
| Delayed switching. | 0 to 1000 (0x00 to 0x03E8) <i>(in tenths of seconds).</i> | 26 | 40014 | B1 | - | B0 | - | |
| | | 27 | | B0 | | B1 | | |
| Activation time. | 0 to 1000 (0x00 to 0x03E8) <i>(in tenths of seconds).</i> | 28 | 40015 | B1 | - | B0 | - | |
| | | 29 | | B0 | | B1 | | |

| VALUE | MEANING |
|-----------|---|
| 0 (0x00) | No function. |
| 1 (0x01) | Setpoint on gross weight. |
| 2 (0x02) | Setpoint on net weight. |
| 4 (0x04) | Gross weight at zero. |
| 5 (0x05) | Net weight at zero. |
| 6 (0x06) | Moving weight. |
| 23 (0x17) | Print key pressed. |
| 25 (0x19) | Mode key pressed. |
| 26 (0x1A) | C key pressed. |
| 27 (0x1B) | Zero key pressed. |
| 28 (0x1C) | Tare key pressed. |
| 29 (0x1D) | Error. |
| 30 (0x1E) | Setpoint in net weight if a tare was set. |

3. To save the parameters:

- Write in Bytes 2 to 5 (PARAMETER 1) the value **5102** (0x13EE) and send the command **56** (0x38) "SAVE PAGE".
- Send the command **28** (0x1C) "SAVE SETUP".

Profinet Name

1. Write in Bytes 16 to 31 of the Output Area the new Profinet name of the transmitter.
2. Write in Bytes 2 to 5 (PARAMETER 1) the value **5031** (0x13A7) and send the command **56** (0x38) "**SAVE PAGE**".

| Parameter | | Page | Byte |
|--------------------|-----------------|------|------|
| Description | Possible values | | |
| Command SAVE PAGE | 00 | | 0 |
| | 38 | | 1 |
| Page 5031 (0x13A7) | 0 | | 2 |
| | 0 | | 3 |
| | 13 | | 4 |
| | A7 | | 5 |

| Parameter | | Page | Byte |
|---|-----------------|-------------------------|------|
| Description | Possible values | | |
| Profinet name to be assigned to the transmitter, insert up to 16 ASCII characters in hex format. Allowed characters: <ul style="list-style-type: none"> • a to z (lowercase) • 0 to 9 • "-" If the length of the Profinet name is less than 16 characters, fill the remaining Bytes with the value 0. In the example: ricelake-0123456 | r (0x72) | 5031 (0x13A7) | 16 |
| | i (0x69) | | 17 |
| | c (0x63) | | 18 |
| | e (0x65) | | 19 |
| | l (0x6C) | | 20 |
| | a (0x61) | | 21 |
| | k (0x6B) | | 22 |
| | e (0x65) | | 23 |
| | - (0x2D) | | 24 |
| | 0 (0x30) | | 25 |
| | 1 (0x31) | | 26 |
| | 2 (0x32) | | 27 |
| | 3 (0x33) | | 28 |
| | 4 (0x34) | | 29 |
| | 5 (0x35) | | 30 |
| | 6 (0x36) | | 31 |

3. Save the parameters:
 - Send the command **28** (0x1C) "**SAVE SETUP**".
 - Reboot the transmitter (command **34** (0x22)).

Scale Zeroing via Fieldbus

- Send the command **1** (0x01) "**ZERO**".

i **Note:** This command does not affect calibration. Once the device is turned off, the performed zeroing gets lost.

Mechanical Tare Zeroing via Fieldbus

- Send command **35** (0x23) "**DATA READING**".
- Send command **39** (0x27) "**ZERO CALIBRATION**".
- Verify that, in page **5001** (0x1389) in the Input Area, the value in Bytes 30 - 31 turns from 6 (0x06) "Ongoing zero calibration" into 4 (0x04) "Calibration OK".
- Send command **36** (0x24) "**DATA WRITING AND STORAGE**" inserting in PARAMETER 1 the value 0 (0x00).

i **Note:** Unlike ZERO command, the ZERO CALIBRATION command affects the scale calibration and finalises the modification of the zero point.

Backup

It is possible to **copy the device setup** by reading in sequence all setup pages from 0 to 255 (0x00 to 0xFF).

1. Send the command **26** (0x1A) "**SETUP READING**" inserting in PARAMETER 1 the value 0 (0x00) "first setup page".
2. Copy data in Bytes 16 to 31 of page 0 (0x00) "Input Area".
3. Send the command **26** (0x1A) "**SETUP READING**" inserting in PARAMETER 1 the value 1 (0x01) "second setup page".
4. Copy data in Bytes 16 to 31 of page 1 (0x01) "Input Area".
5. Repeat this procedure for all the other pages.

Restore

To restore the backup, write in sequence all setup pages:

1. Copy in Bytes 16 to 31 of the Output Area previously saved data in page 0 (0x00).
2. Send the command **27** (0x1B) "**SETUP WRITING**" inserting in PARAMETER 1 the value 0 (0x00).
3. Copy in Bytes 16 to 31 of the Output Area previously saved data in page 1 (0x01).
4. Send the command **27** (0x1B) "**SETUP WRITING**" inserting in PARAMETER 1 the value 1 (0x01).
5. Repeat this procedure for all the other pages.

Diagnostic Messages

OPERATING MESSAGES

| Message | Description |
|-----------------|------------------------------------|
| <i>F.b.Conn</i> | Fieldbus in operation. |
| <i>F.b.on</i> | Communication with active network. |
| <i>F.buS.in</i> | Module initialisation. |

ERROR MESSAGES

| Message | Description |
|-----------------------|--------------------------------|
| <i>F.buS.Er</i> | Fielbus not in operation. |
| <i>F.b.Err</i> + code | Error status, see error codes. |

| Code | Description |
|---------------|--|
| <i>1000</i> | Module fatal error. Restart the device. |
| <i>1001</i> | Selected protocol differs from the one managed by the module. Check step <i>FLd.buS</i> . |
| <i>1005</i> | Internal communication error between fieldbus module and CPU board. Reboot the device. If the error persists, contact service. |
| <i>000140</i> | General network error. Check network connections. |
| <i>000141</i> | Closed connection. |
| <i>000142</i> | Connection in timeout. |
| <i>000143</i> | Isolated network. |
| <i>000144</i> | Duplicated node. |
| <i>000145</i> | Network cable unplugged. |



© Rice Lake Weighing Systems Content subject to change without notice.

230 W. Coleman St. • Rice Lake, WI 54868 • USA USA: 800-472-6703 • International: +1-715-234-9171